# Axiomatization of Independence Systems by Map Functions

A. Morshinin Sobolev Institute of Mathematics SB RAS Omsk-2023 The research was supported by RSF grant 22-71-10015

## Independence System

U – nonempty finite set,  $\mathbf{A} \subseteq 2^{U}$  – nonempty indexed family of subsets with an *independence axiom* 

$$A_1 \in \mathbf{A}, A_2 \subseteq A_1 \Rightarrow A_2 \in \mathbf{A}.$$

A – independent subsets.

A set  $\mathbf{D} = \mathbf{2}^{\mathbf{U}} \setminus \mathbf{A}$  is satisfied

$$D_1 \in \mathbf{D}, D_1 \subseteq D_2 \Rightarrow D_2 \in \mathbf{D}.$$

- **D** dependent subsets.
- $\mathbf{B}$  *bases* or maximal independent subsets.
- C *circuities* or minimal dependent subsets.

 $S = (U, \mathbf{A}), S = (U, \mathbf{B}), S = (U, \mathbf{C}) \text{ and } S = (U, \mathbf{D}) \text{ are equals$ *independence systems*.

## Independence System

For any subset  $X \subseteq U$  let  $\mathbf{B}_{\mathbf{X}}$  be a set of all maximal independent *subsets* of X (i.e.  $\mathbf{B}_{\mathbf{X}}$  is *bases* of X).

For any subset  $X \subseteq U$  let  $C_X$  be a set of all minimal dependent *supersets* of X (i.e.  $C_X$  is *circuities* of X).



## Graph Independence System

Example. Let G = (V, E) be a graph. A subset  $I \subseteq V$  is an *independent set* if  $uv \notin E$  for any  $u, v \in I$ . A system S = (V, A) where A is a family of all independent subsets in G is an independence system.

$$\mathbf{A} = \{ \emptyset, \{1\}, \{2\}, \{3\}, \{1,2\} \}$$
$$\mathbf{D} = \{ \{1,3\}, \{2,3\}, \{1,2,3\} \}$$
$$\mathbf{B} = \{ \{3\}, \{1,2\} \}$$
$$\mathbf{C} = \{ \{1,3\}, \{2,3\} \}$$



# **Optimization Problems For Independence Systems**

Many optimization problems are equivalent to a problem of finding a *base of maximal weight* or a *circuity of minimal weight*.

MAXIMAL INDEPENDENT SET PROBLEM: find maximal independent set in a graph.

For example,  $\{1,2\}$  - maximal independent set.

It is easy to see that  $\{1,2\}$  - base of maximal weight (let all weights be equal to 1).

This problem is NP-hard (in general).



## Graph Matroid

*Matroid* is an independence system  $S = (U, \mathbf{A})$  if all bases of any  $W \subseteq U$  have an equal cardinality.



## Maximal Weighted Independent Set

We can find a base of maximal weight by a *greedy* algorithm in a matroid if an objective function is *additive* (Rado-Edmonds).

In general, we can't find optimal solution by a greedy  $^{3(2)}$   $^{4(4)}$ algorithm, but we can use it for approximation algorithms.  $^{1(3)}$ 

## Maximal Weighted Independent Set



## Matroid and Rank Function

 $M = (U, \mathbf{A})$  is a matroid.  $\mathbf{r}: \mathbf{2}^{\mathbf{U}} \to \mathbb{Z}_+$  is a *rank function* that for each  $X \in U$  maps  $\mathbf{r}(X)$  – cardinality of any base  $B \subseteq X$ . Here

$$\mathbf{A} = \{ A \subseteq U \mid \mathbf{r}(A) = |A| \} (1).$$

## Theorem.

1)  $M = (U, \mathbf{A})$  is a matroid. Then a rank function  $\mathbf{r}: \mathbf{2}^{U} \to \mathbb{Z}_{+}$  defined with

$$\mathbf{r}(X) = \max\{|B|: B \subseteq X, B \in \mathbf{B}_{\mathbf{X}}\} \ (2).$$

for each *X*,  $Y \subseteq U$  satisfies:

 $(\mathbf{r}1) \mathbf{r}(X) \leq |X|,$ 

(r2)  $X \subseteq Y \Rightarrow \mathbf{r}(X) \le \mathbf{r}(Y)$  (monotonic),

(r3)  $\mathbf{r}(X \cup Y) + \mathbf{r}(X \cap Y) \le \mathbf{r}(X) + \mathbf{r}(Y)$  (submodular).

2) **r** is a rank function (2) and it satisfies (r1)-(r3). Then **A** defines with (1) is an indexed family of independent subsets of a matroid.

## Rank Function For Graph Matroid

Let's calculate rank for M = (V, A), where  $V = \{1, 2, 3\}$ .  $\mathbf{B}_{V} = \{\{1, 2\}, \{1, 3\}\}\}$   $\mathbf{r}(\underline{\emptyset}) = 0;$   $\mathbf{r}(\underline{\{1\}}) = \mathbf{r}(\underline{\{2\}}) = \mathbf{r}(\underline{\{3\}}) = 1;$   $\mathbf{r}(\underline{\{1, 2\}}) = 2;$   $\mathbf{r}(\{1, 3\}) = 1;$   $\mathbf{r}(\underline{\{2, 3\}}) = 2;$  $\mathbf{r}(\{1, 2, 3\}) = 2.$ 



2 •

## Independence System and Rank Functions

For an independence system  $S = (U, \mathbf{A})$  we define two functions.

$$\mathbf{r}_{\mathbf{u}}(X) = \max\{|B| : B \subseteq X, B \in \mathbf{B}_{\mathbf{X}}\}\$$
 - upper rank  
 $\mathbf{r}_{\mathbf{l}}(X) = \min\{|B| : B \subseteq X, B \in \mathbf{B}_{\mathbf{X}}\}\$  - lower rank

## Theorem.

Let S = (U, A) be an independence system. Then the following conditions are equivalent:

- 1. *S* is a matroid;
- 2.  $\mathbf{r}_{\mathbf{u}}$  and  $\mathbf{r}_{\mathbf{l}}$  are equals;
- 3.  $\mathbf{r}_{\mathbf{u}}$  is submodular.

## Independence System and Upper Rank Function

If  $S = (U, \mathbf{A})$  is not a matroid then  $\mathbf{r}_{\mathbf{u}}$  satisfies (r1)-(r2) and doesn't satisfy (r3).  $\mathbf{r}_{\mathbf{u}}(\underline{\emptyset}) = 0;$   $\mathbf{r}_{\mathbf{u}}(\underline{\{1,2\}}) = \mathbf{r}_{\mathbf{u}}(\underline{\{2\}}) = \mathbf{r}_{\mathbf{u}}(\underline{\{3\}}) = 1;$   $\mathbf{r}_{\mathbf{u}}(\underline{\{1,3\}}) = 1;$   $\mathbf{r}_{\mathbf{u}}(\underline{\{2,3\}}) = 1;$   $\mathbf{r}_{\mathbf{u}}(\underline{\{1,2,3\}}) = 2.$   $\mathbf{r}_{\mathbf{u}}(\underline{\{1,2,3\}}) = 2.$  $\mathbf{r}_{\mathbf{u}}(\underline{\{1,3\}}) + \mathbf{r}_{\mathbf{u}}(\underline{\{2,3\}}) < \mathbf{r}_{\mathbf{u}}(\underline{\{1,2,3\}}) + \mathbf{r}_{\mathbf{u}}(\underline{\{3\}}).$ 

## Independence System and Upper Rank Function

 $S = (U, \mathbf{A})$  is an independence system.  $\mathbf{r}_{\mathbf{u}}: \mathbf{2}^{\mathbf{U}} \to \mathbb{Z}_{+}$  is an *upper rank function*. Here

$$\mathbf{A} = \{ A \subseteq U \mid \mathbf{r}_{\mathbf{u}}(A) = |A| \} \ (1)$$

#### Theorem.

1)  $S = (U, \mathbf{A})$  is an independence system. Then an upper rank function  $\mathbf{r}_{\mathbf{u}}: \mathbf{2}^{\mathbf{U}} \to \mathbb{Z}_{+}$  defined with  $(X) = \max\{|B| : B \subseteq X, B \in \mathbf{B}_{\mathbf{x}}\} (2).$ 

$$\mathbf{r}_{\mathbf{u}}(X) = \max\{|B| : B \subseteq X, B \in \mathbf{B}_{\mathbf{X}}\}\$$

for each *X*,  $Y \subseteq U$  satisfies:

(r1)  $\mathbf{r}_{\mathbf{u}}(X) \leq |X|$ ,

(r2)  $X \subseteq Y \Rightarrow \mathbf{r}_{\mathbf{u}}(X) \leq \mathbf{r}_{\mathbf{u}}(Y)$ ,

(r3)  $\mathbf{r}_{\mathbf{u}}(X \cup Y) \leq \mathbf{r}_{\mathbf{u}}(X) + \mathbf{r}_{\mathbf{u}}(Y).$ 

2)  $\mathbf{r}_{\mu}$  is an upper rank function (2) and it satisfies (r1)-(r3). Then A defines with (1) is an indexed family of independent subsets of an independence system.

## Comatroid

*Comatroid* is an independence system  $S = (U, \mathbf{D})$  if all circuities of any  $W \subseteq U$  have an equal cardinality.

Example. Let G = (V, E) be a graph. A subset  $I \subseteq V$  is a *cover set* of V if for each  $uv \in E$ :  $u \in V$  or  $v \in V$  or  $u, v \in V$ . A system  $S = (V, \mathbf{D})$  where  $\mathbf{D}$  is a family of all cover sets in G is an independence system.

# Graph Comatroid

A graph independent system is a comatroid if and only if the graph is a cluster graph.

 $\mathbf{C} = \{\{1,3\}, \{1,4\}, \{2,3\}, \{2,4\}\}$ 

We can find a circuity of minimal weight by a *reverse greedy* algorithm in a comatroid if an objective function is *additive* (Rado-Edmonds).

In general, we can't find optimal solution by the reverse greedy algorithm, but we can use it for approximation <sup>3</sup>(3) • • • • • • (1) algorithms.

5 (3)

- 2 (5)

1 (2)

## Graph Comatroid



## **Comatroid and Girth Function**

 $CM = (U, \mathbf{A})$  is a comatroid.  $\mathbf{g}: \mathbf{2}^{\mathbf{U}} \to \mathbb{Z}_+$  is a *girth function* that for each  $X \in U$  maps  $\mathbf{g}(X)$  – cardinality of any circus  $X \subseteq C$ . Here

$$\mathbf{D} = \{ D \subseteq U \mid \mathbf{g}(D) = |D| \} (1).$$

## Theorem.

1)  $CM = (U, \mathbf{D})$  is a comatroid. Then a girth function  $\mathbf{g}: 2^U \to \mathbb{Z}_+$  defined with  $\mathbf{g}(X) = \min\{|C| : X \subseteq C, C \in \mathbf{C}_X\}$  (2).

for each *X*,  $Y \subseteq U$  satisfies:

 $(g1) \mathbf{g}(X) \ge |X|,$ 

(g2)  $X \subseteq Y \Rightarrow \mathbf{g}(X) \leq \mathbf{g}(Y)$  (monotonic),

(g3)  $\mathbf{g}(X \cup Y) + \mathbf{g}(X \cap Y) \ge \mathbf{g}(X) + \mathbf{g}(Y)$  (supermodular).

2) **g** is a girth function (2) and it satisfies (g1)-(g3). Then **D** defines with (1) is an indexed family of dependent subsets of a comatroid.

## Plans

- 1. Independence system by the grid function.
- 2. Independence system by the interior operator.